

# Magnetostatics -

- ① Bio savart's law. ✓
  - ② Ampere's law. ✓
  - ③ vector Poisson Equation
  - ③ magnetic vector potential
- ① Bio-Savart's law.

$$\underline{\vec{A}} \times \underline{\vec{B}} = \underline{\vec{C}}$$

Screwdriver

$$I dl \sin \alpha = |Idl| |\hat{a}_R| \sin \alpha$$

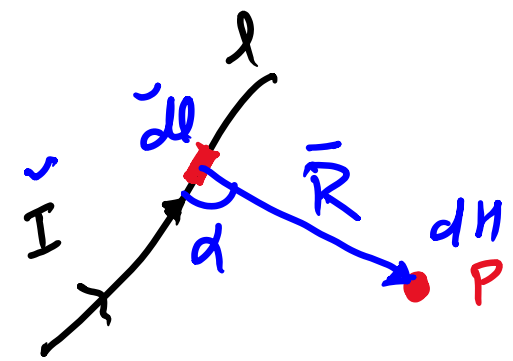
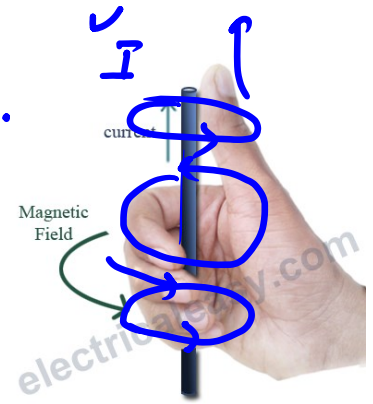
$$= I dl \times \hat{a}_R$$

$$dH = \frac{I dl \times \hat{a}_R}{4\pi R^2}$$

$$\hat{a}_R = \frac{\vec{R}}{|\vec{R}|}$$

$$dH = \frac{I dl \times \vec{R}}{4\pi R^3}$$

$$H = \int \frac{I dl \times \vec{R}}{4\pi R^3}$$



$$k = \frac{1}{4\pi}$$

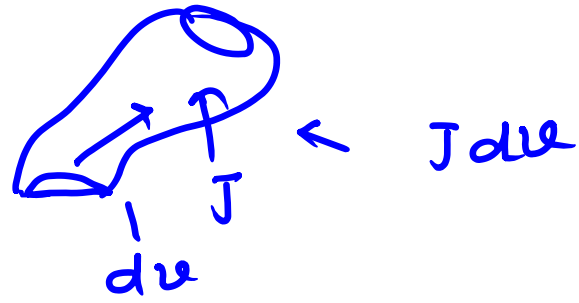
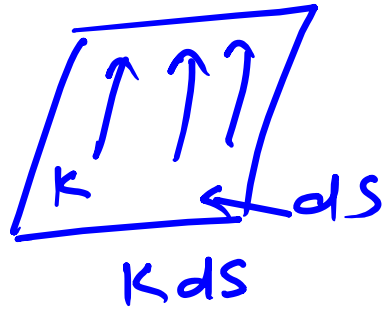
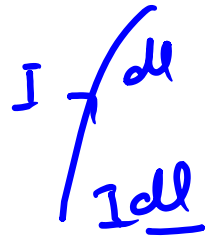
$$dH \propto Idl$$

$$dH \propto \sin \alpha$$

$$dH \propto \frac{1}{R^2}$$

$$dH \propto \frac{Idl \sin \alpha}{R^2}$$

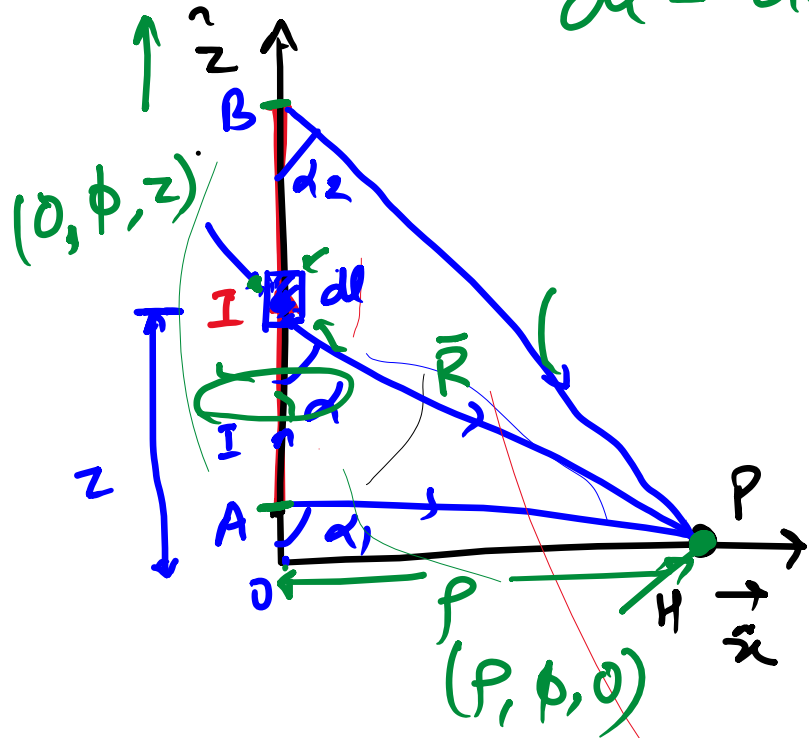
$$dH = \frac{Idl \sin \alpha}{4\pi R^2}$$



$$H = \int \frac{I \, dl \times \hat{a}_R}{4\pi R^2}$$

$$H = \int \frac{K \, ds \times \hat{a}_R}{4\pi R^2}$$

$$H = \int \frac{J \, du \times \hat{a}_R}{4\pi R^2}$$



$$dl = dz \hat{z} \quad H = \int \frac{I dl \times \hat{r}}{4\pi R^2} \quad \hat{r} = \frac{\vec{R}}{|\vec{R}|}$$

$$\vec{R} = (p-0)\hat{p} + (\phi-\phi)\hat{\phi} + (0-z)\hat{z}$$

$$\vec{R} = p\hat{p} - z\hat{z}$$

$$H = \int \frac{I (\hat{z} dz) \times (p\hat{p} - z\hat{z})}{4\pi (p^2 + z^2)^{3/2}}$$

$$\vec{dl} \times \vec{R} = \begin{vmatrix} \hat{p} & \hat{\phi} & \hat{z} \\ 0 & 0 & dz \\ p & 0 & -z \end{vmatrix} = \hat{p}(0) + \hat{\phi}(p dz) + \hat{z}(0) = \hat{\phi} p dz$$

$$H = \int \frac{I \hat{\phi} p dz}{4\pi (p^2 + z^2)^{3/2}}$$

Let  $z = \rho e^{i\alpha}$

$dz = -\rho \operatorname{cosec}^2 \alpha d\alpha$

$H = \int_{\alpha_1}^{\alpha_2} \frac{-I \rho^2 \operatorname{cosec}^2 \alpha d\alpha}{4\pi(\rho^2 + \rho^2 \cot^2 \alpha)^{3/2}} \hat{\phi}$

$H = \int \frac{-I \rho^2 \operatorname{cosec}^2 \alpha d\alpha}{4\pi \rho^3 \operatorname{cosec}^3 \alpha} \hat{\phi}$

$H = \int \frac{-I d\alpha}{4\pi \rho \operatorname{cosec} \alpha} \hat{\phi}$

$H = -\frac{I}{4\pi \rho} \int_{\alpha_1}^{\alpha_2} \sin \alpha d\alpha \hat{\phi}$

①  $\rho \rightarrow \infty$

$\alpha_1 = 90^\circ, \alpha_2 = 0^\circ$

$H = \frac{I}{4\pi \rho} \hat{\phi}$

②  $\rho \rightarrow -\infty \text{ to } \infty$

$\alpha_1 = 180^\circ, \alpha_2 = 0^\circ$

$H = \frac{I}{2\pi \rho} \hat{\phi}$

Example  $\rightarrow$  7.1, 7.2, 7.3, 7.4

Ampere's law - The line integral of tangential component of H around a closed path is the same as current enclosed by the path.

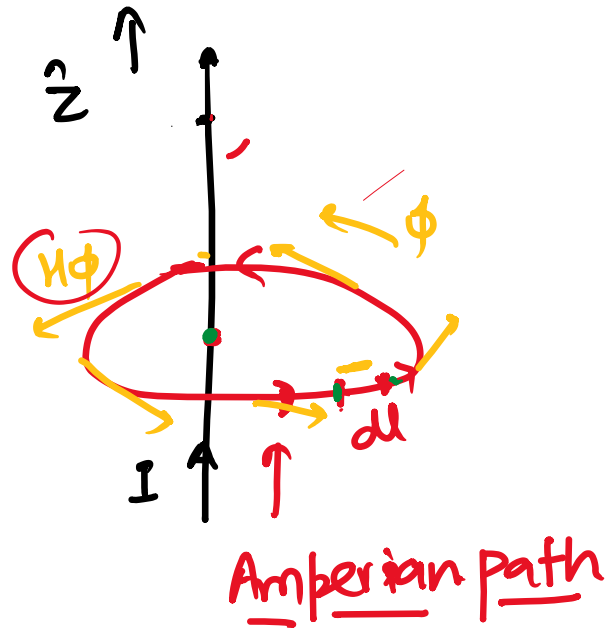
$$\int_S \underline{D} \cdot d\underline{S} = \underline{Q}_{enc}$$

$$\oint \underline{H} \cdot d\underline{l} = I_{enc} = \int_S \underline{J} \cdot d\underline{S}$$

$$\int_S \nabla \times \underline{H} \cdot d\underline{S} = \int_S \underline{J} \cdot d\underline{S}$$

$\boxed{\nabla \times \underline{H} = \underline{J}}$   $\leftrightarrow$  Ampere's circuital law.

# Applications of Ampere's law -



$$I = \oint \mathbf{H} \cdot d\mathbf{l} = \oint H_{\phi} \hat{\phi}$$

$$d\mathbf{l} = \rho d\phi \hat{\phi}$$

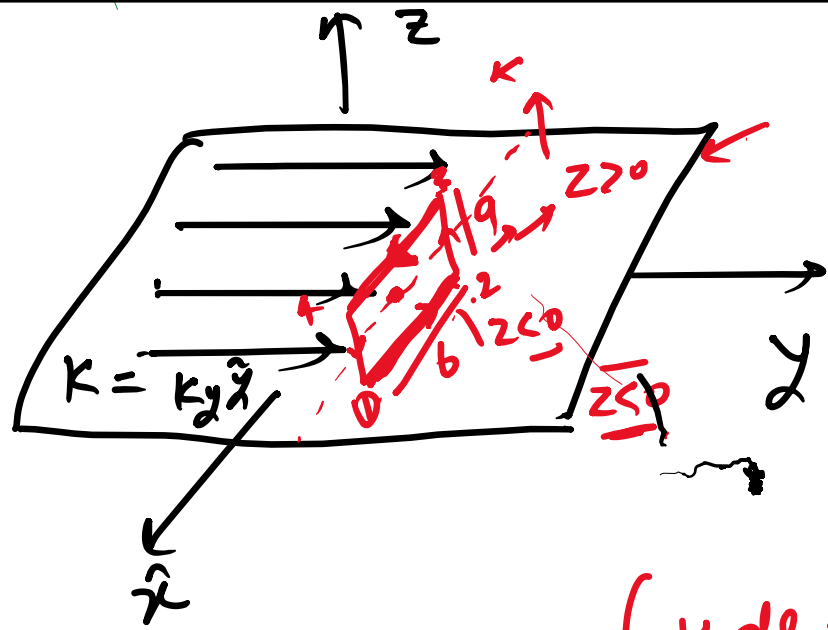
$$I = \oint H_{\phi} \hat{\phi} \cdot \rho d\phi \hat{\phi}$$

$$I = \int_0^{2\pi} H_{\phi} \rho d\phi$$

$$I = H_{\phi} \cdot 2\pi \rho$$

$$\Rightarrow H_{\phi} = \frac{I}{2\pi \rho}$$

$$\boxed{H = \frac{I}{2\pi \rho} \hat{\phi}}$$



$$\oint \vec{H} \cdot d\vec{l} = I_{enc} = \vec{K}_y b \quad \text{--- (1)}$$

$$\vec{H} = \begin{cases} H_0 \hat{x} & z > 0 \\ -H_0 \hat{x} & z < 0 \end{cases} \quad \text{--- (2)}$$

$$\oint \vec{H} \cdot d\vec{l} = \left\{ \int_1^2 + \int_2^3 + \int_3^4 + \int_4^1 \right\} \vec{H} \cdot d\vec{l}$$

$$= +H_0(b) + 0(a) + H_0(+b) + 0$$

$$= H_0 b + H_0 b = 2H_0 b \quad \text{--- (3)}$$

$$2H_0 b = K_y b$$

$$H_0 = \frac{K_y}{2}$$

$$\vec{H} = \begin{cases} \frac{K_y}{2} \hat{x}; & z > 0 \\ -\frac{K_y}{2} \hat{x}; & z < 0 \end{cases}$$

A

Calculate the magnetic field in a coaxial wire - H.W.

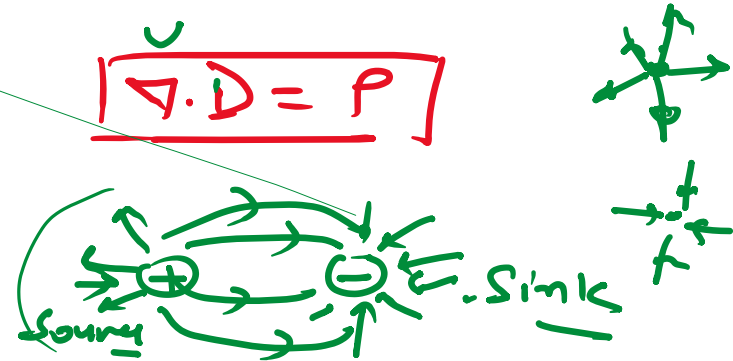
magnetic flux density (Maxwell's equation) →

$$\nabla \cdot \mathbf{D} = \rho$$

$$\Psi = \oint \mathbf{B} \cdot d\mathbf{S}$$

$$\mathbf{B} = \frac{\Psi}{\int d\mathbf{S}}$$

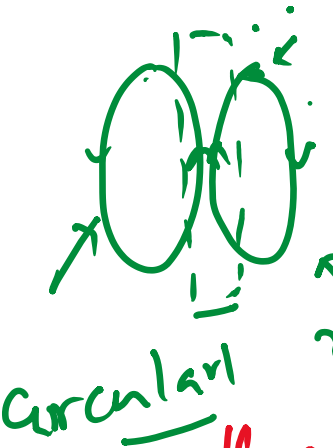
$$\nabla \cdot \mathbf{D} = \rho$$



$$\mu_0 = 4\pi \times 10^{-7} \text{ H/m}$$

$$\mathbf{B} = \mu_0 \mathbf{H}$$

no source / no sink

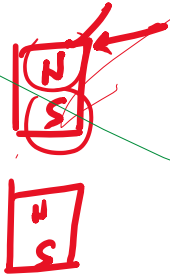
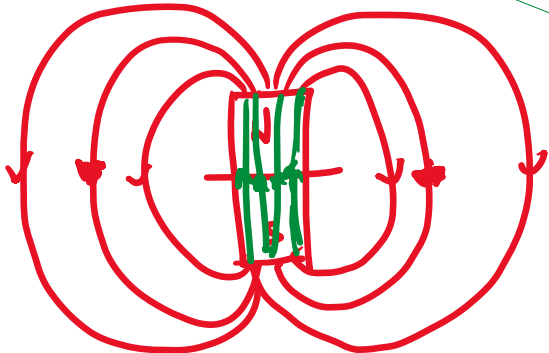


"Magnetic monopole does not exist"

Divergence -

$$\nabla \cdot \mathbf{B} = 0$$

↑ Maxwell's equation.





$$\nabla \cdot D = \rho \quad \text{Static field}$$

$$\nabla \times E = 0 \checkmark$$

$$\nabla \cdot B = 0 \checkmark$$

$$\psi = \int B \cdot ds$$

$\nabla \cdot B = 0 \rightarrow$  Gauss's law of magnetostatics.

$$\left. \begin{array}{l} \nabla \cdot D = \rho \\ \nabla \cdot B = 0 \end{array} \right\}$$

$$\int \nabla \cdot B \, dv = 0$$

$$= \oint_S \underline{B \cdot ds} = \underline{0}:$$

Total magnetic flux enclosed by any surface remains zero.

## In static fields

- ①  $\rightarrow \nabla \cdot \mathbf{D} = \rho_v \leftarrow$  Gauss's law of Electrostatics  $\leftarrow \frac{\rho}{\epsilon_0}$
- ②  $\nabla \times \mathbf{E} = 0 \leftarrow$  Conservation of electric field.  $\rightarrow \mathbf{E} = -\nabla V \rightarrow$
- ③  $\nabla \cdot \mathbf{B} = 0 \leftarrow$  Gauss's law of magnetostatics.
- ④  $\nabla \times \mathbf{H} = \mathbf{J} \leftarrow$  Ampere's Circuital Law.

maxwell's equations in static fields.  $\leftarrow$  Point form  
or Differential form.

- ①  $\oint \mathbf{D} \cdot d\mathbf{S} = Q_{enc.}$
  - ②  $\oint \mathbf{E} \cdot d\mathbf{l} = 0$
  - ③  $\oint \mathbf{B} \cdot d\mathbf{S} = 0$
  - ④  $\oint \mathbf{H} \cdot d\mathbf{l} = I_{enc.}$
- Integral form of maxwell's Equation.

# Magnetic Scalar & Vector Potentials

$$\vec{B} = \mu_0 H \quad A/m$$

↑  
magnetic field intensity

$V \rightarrow$  scalar potential

$\vec{A} \rightarrow$  vector potential

$B \rightarrow$  magnetic flux density

$$B = \mu_0 H$$

$$\hat{a}_R = \frac{\vec{R}}{|\vec{R}|}$$

$$\nabla \times (\nabla V) = 0$$

$$\nabla \cdot (\nabla \times \vec{A}) = 0 \quad \text{--- (1)}$$

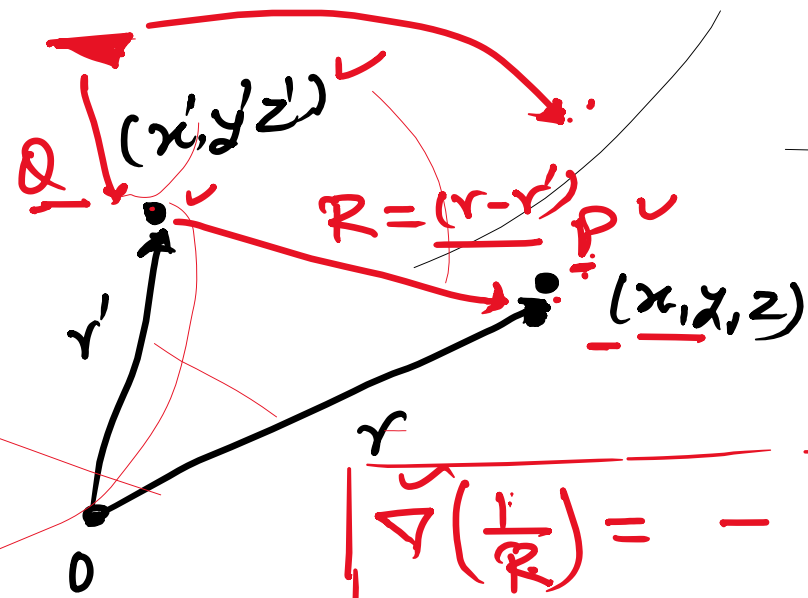
$$\nabla \cdot \vec{B} = 0 \quad \text{--- (2)}$$

$$\boxed{\vec{B} = \nabla \times \vec{A}}$$

$$H = \int \frac{I d\vec{l} \times \vec{R}}{4\pi R^3}$$

$$\nabla \times \vec{A} = \vec{B} = \int \frac{\mu_0 I d\vec{l} \times \hat{a}_R}{4\pi R^2}$$

$$\vec{B} = \int \frac{\mu_0 I}{4\pi} \left( d\vec{l} \times \frac{\hat{a}_R}{R^2} \right)$$



$$\boxed{\nabla \left( \frac{1}{R} \right) = - \frac{\hat{a}_R}{R^2}}$$

$$\vec{R} = (x-x')\hat{x} + (y-y')\hat{y} + (z-z')\hat{z}$$

$$\vec{B} = \frac{\mu_0}{4\pi} \int_L \left\{ \vec{I} d\vec{l}' \times \nabla \left( \frac{1}{R} \right) \right\} \quad \text{--- ①}$$

$f \rightarrow$  Scalar  
 $\vec{F} \rightarrow$  Vector

$$\nabla \times (f \vec{F}) = \underbrace{f \nabla \times \vec{F}} + \underbrace{(\nabla f) \times \vec{F}}$$

$$\left[ \begin{array}{c} \vec{y} \cdot \vec{z} \\ \vec{z} \end{array} \right] + \left[ \begin{array}{c} \vec{x} \times \vec{F} \\ \vec{F} \end{array} \right]$$

$$f = \frac{1}{R}$$

$$\vec{F} = d\vec{l}'$$

$$\nabla \times (f \vec{F}) = f \nabla \times \vec{F} + (\nabla f) \times \vec{F}$$

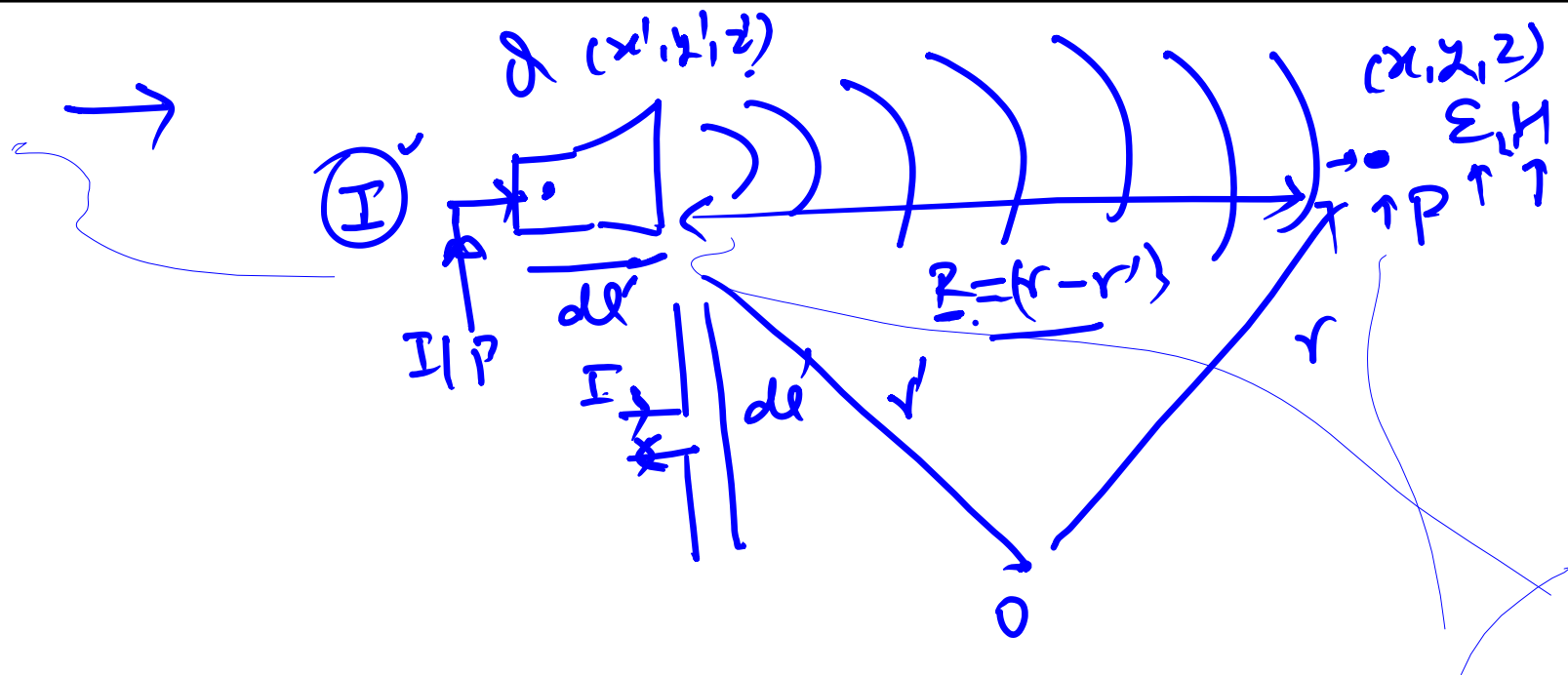
$$\nabla \times \left( \frac{1}{R} d\vec{l}' \right) = \frac{1}{R} \nabla \times d\vec{l}' + \left( \nabla \frac{1}{R} \right) \times d\vec{l}'$$

$$\nabla \times d\vec{l}' = 0$$

$\uparrow$   $(x, y, z)$       $\uparrow$   $(x', y', z')$

$$d\vec{l}' \times \nabla \left( \frac{1}{R} \right) = - \nabla \times d\vec{l}'$$

$$\vec{B} = \nabla \times \int_L \frac{\mu_0 \vec{I} d\vec{l}'}{4\pi R} = \nabla \times \vec{A} \Rightarrow \boxed{\vec{A} = \int_L \frac{\mu_0 \vec{I} d\vec{l}'}{4\pi R}}$$



Antenna Engineering.

$$\underline{\underline{\bar{R}}} = \underline{r} - \underline{r}'$$

$$\underline{\underline{\bar{A}}} = \int \frac{\mu_0 I dl'}{4\pi \bar{R}}$$

$$\underline{\underline{\bar{B}}} = \nabla \times \underline{\underline{\bar{A}}}$$

$$\underline{\underline{\bar{B}}} = \mu_0 \underline{\underline{H}}$$

$$\left[ \nabla \times \underline{\underline{E}} = -\frac{\partial \underline{\underline{B}}}{\partial t} \right]$$

$$\underline{\underline{\nabla}} \times \underline{\underline{H}} = \underline{\underline{J}} = \sigma \underline{\underline{E}}$$

Assignment → Solve all the solved & unsolved  
numerical problems of chapter 7

by <sup>SMTI</sup>  
Sadiqy.

